

Machine-Level Representation of Programs: Control

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Class session plan

- ▶ Tuesday, 3/26: Control flow (conditionals, if, for, while, do loops, switch statements) in assembly. (Book chapter 3.6). Bomblab phase_2, phase_3.
- ▶ Thursday, 3/28: Function calls in assembly. (Book chapter 3.7). Bomblab phase_4.
- ▶ Tuesday, 4/2: Arrays and data structures in assembly. (Book chapter 3.8). Bomblab phase_5, phase_6.

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Carnegie Mellon

Address Computation Instruction

- **leaq Src, Dst**
 - Src is address mode expression
 - Set Dst to address denoted by expression
- **Uses**
 - Computing addresses without a memory reference
 - E.g., translation of `p = &x[i];`
 - Computing arithmetic expressions of the form $x + k*y$
 - $k = 1, 2, 4, \text{ or } 8$
- **Example**

```
long m12(long x)
{
    return x*12;
}
```

Converted to ASM by compiler:

```
leaq (%rdi,%rdi,2), %rax # t <- x+x*2
salq $2, %rax           # return t<<2
```

Example: 3_leaq.c

Load effective address

```
1 long * leaq (  
2     long * ptr, long index  
3 ) {  
4     return &ptr[index+1];  
5 }
```

```
1 long mulAdd (  
2     long base, long index  
3 ) {  
4     return base+index*8+8;  
5 }
```

Both C code functions above translate to the assembly on the right.

leaq:

mulAdd:

```
leaq 8(%rdi,%rsi,8), %rax  
ret
```

Explanation

- ▶ `leaq src, dest` takes the effective address of the memory (index, displacement) expression of `src` and puts it in `dest`.
- ▶ `leaq` has shorter latency (takes fewer CPU cycles) than `imulq`, so GCC will use `leaq` whenever it can to calculate expressions like $y + ax + b$.

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What is control flow?

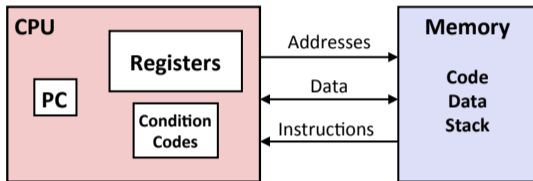
Control flow is:

- ▶ Change in the sequential execution of instructions.
- ▶ Change in the steady incrementation of the program counter / instruction pointer (%rip register).

Control primitives in assembly build up to enable C and Java control statements:

- ▶ if-else statements
- ▶ do-while loops
- ▶ while loops
- ▶ for loops
- ▶ switch statements

Assembly/Machine Code View



Programmer-Visible State

- **PC: Program counter**
 - Address of next instruction
 - Called "RIP" (x86-64)
- **Register file**
 - Heavily used program data
- **Condition codes**
 - Store status information about most recent arithmetic or logical operation
 - Used for conditional branching
- **Memory**
 - Byte addressable array
 - Code and user data
 - Stack to support procedures

Condition codes

Automatically set by most arithmetic instructions.

Applicable types	Condition code	Name	Use
Signed and unsigned	ZF	Zero flag	The most recent operation yielded zero.
Unsigned types	CF	Carry flag	The most recent operation generated a carry out of the most significant bit. Used to detect overflow for unsigned operations
Signed types	SF	Sign flag	The most recent operation yielded a negative value.
Signed types	OF	Overflow flag	The most recent operation yielded a two's complement positive or negative overflow.

Table: Condition codes important for control flow

Comparison instructions

```
cmpq source1, source2
```

Performs $\text{source2} - \text{source1}$, and sets the condition codes without setting any destination register.

Test for equality

```
1 short equal_sl (  
2     long x,  
3     long y  
4 ) {  
5     return x==y;  
6 }
```

C code function above translates to the assembly on the right.

```
equal_sl:  
    xorl %eax, %eax  
    cmpq %rsi, %rdi  
    sete %al  
    ret
```

Explanation

- ▶ `xorl %eax, %eax`: Zeros the 32-bit register `%eax`.
- ▶ `cmpq %rsi, %rdi`: Calculates $\%rdi - \%rsi$ ($x - y$), sets condition codes without updating any destination register.
- ▶ `sete %al`: Sets the 8-bit `%al` subset of `%eax` if op yielded zero.

Test if unsigned x is below unsigned y

```
1 short below_ul (  
2     unsigned long x,  
3     unsigned long y  
4 ) {  
5     return x<y;  
6 }
```

```
1 short nae_ul (  
2     unsigned long x,  
3     unsigned long y  
4 ) {  
5     return !(x>=y);  
6 }
```

Both C code functions above translate to the assembly on the right.

```
below_ul:  
nae_ul:  
    xorl %eax, %eax  
    cmpq %rsi, %rdi  
    setb %al  
    ret
```

Explanation

- ▶ `xorl %eax, %eax`: Zeros `%eax`.
- ▶ `cmpq %rsi, %rdi`: Calculates `%rdi - %rsi` ($x - y$), sets condition codes without updating any destination register.
- ▶ `setb %al`: Sets `%al` if CF flag set indicating unsigned overflow.

Side review: De Morgan's laws

▶ $\neg A \wedge \neg B \iff \neg(A \vee B)$

▶ $(\sim A) \& (\sim B) \iff \sim (A|B)$

Set instructions

`cmp source1, source2` performs `source2 - source1`, sets condition codes.

Applicable types	Set instruction	Logical condition	Intuitive condition
Signed and unsigned	<code>sete / setz</code>	ZF	Equal / zero
Signed and unsigned	<code>setne / setnz</code>	\sim ZF	Not equal / not zero
Unsigned	<code>setb / setnae</code>	CF	Below
Unsigned	<code>setbe / setna</code>	CF ZF	Below or equal
Unsigned	<code>seta / setnbe</code>	\sim CF & \sim ZF	Above
Unsigned	<code>setnb / setae</code>	\sim CF	Above or equal
Signed	<code>sets</code>	SF	Negative
Signed	<code>setns</code>	\sim SF	Nonnegative
Signed	<code>setl / setnge</code>	SF ^ OF	Less than
Signed	<code>setle / setng</code>	(SF ^ OF) ZF	Less than or equal
Signed	<code>setg / setnle</code>	\sim (SF ^ OF) & \sim ZF	Greater than
Signed	<code>setge / setnl</code>	\sim (SF ^ OF)	Greater than or equal

Table: Set instructions

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Jumping

■ jX Instructions

- Jump to different part of code depending on condition codes

jX	Condition	Description
jmp	1	Unconditional
je	ZF	Equal / Zero
jne	\sim ZF	Not Equal / Not Zero
js	SF	Negative
jns	\sim SF	Nonnegative
jg	\sim (SF \wedge OF) & \sim ZF	Greater (Signed)
jge	\sim (SF \wedge OF)	Greater or Equal (Signed)
jl	(SF \wedge OF)	Less (Signed)
jle	(SF \wedge OF) ZF	Less or Equal (Signed)
ja	\sim CF & \sim ZF	Above (unsigned)
jb	CF	Below (unsigned)

Branch statements

```
1 unsigned long absdiff_ternary (  
2     unsigned long x, unsigned long y ){  
3     return x<y ? y-x : x-y;  
4 }
```

```
1 unsigned long absdiff_if_else (  
2     unsigned long x, unsigned long y ){  
3     if (x<y) return y-x;  
4     else return x-y;  
5 }
```

```
1 unsigned long absdiff_goto (  
2     unsigned long x, unsigned long y ){  
3     if (!(x<y)) goto Else;  
4     return y-x;  
5     Else:  
6     return x-y;  
7 }
```

All C functions above translate
(-fno-if-conversion) to assembly at right.

```
absdiff_if_else:  
absdiff_goto:  
    cmpq %rsi, %rdi  
    jnb .ELSE  
    movq %rsi, %rax  
    subq %rdi, %rax  
    ret  
.ELSE:  
    movq %rdi, %rax  
    subq %rsi, %rax  
    ret
```

Explanation

- ▶ `cmpq %rsi, %rdi`: Calculates $\%rdi - \%rsi$ ($x - y$), sets condition codes.
- ▶ `jnb .ELSE`: Sets program counter / instruction pointer in `%rip` (`.ELSE`) if CF flag not set indicating no unsigned overflow.

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Conditional move statements

```
1 unsigned long absdiff_ternary (  
2     unsigned long x, unsigned long y ){  
3     return x<y ? y-x : x-y;  
4 }
```

```
1 unsigned long absdiff_if_else (  
2     unsigned long x, unsigned long y ){  
3     if (x<y) return y-x;  
4     else return x-y;  
5 }
```

```
1 unsigned long absdiff_goto (  
2     unsigned long x, unsigned long y ){  
3     if (!(x<y)) goto Else;  
4     return y-x;  
5     Else:  
6     return x-y;  
7 }
```

All C functions above translate
(-fif-conversion or -O1) to assembly at

```
absdiff_ternary:  
absdiff_if_else:  
absdiff_goto:  
    movq %rsi, %rdx // y  
    subq %rdi, %rdx // y-x  
    movq %rdi, %rax // x  
    subq %rsi, %rax // x-y  
    cmpq %rsi, %rdi  
    cmovb %rdx, %rax  
    ret
```

Explanation

- ▶ `cmpq %rsi, %rdi`: Calculates $\%rdi - \%rsi$ ($x - y$), sets condition codes.
- ▶ `jnb .ELSE`: Sets program counter / instruction pointer in `%rip` (.ELSE) if CF flag not set indicating no unsigned overflow.

Modifying control flow vs. data flow in deep CPU pipelines

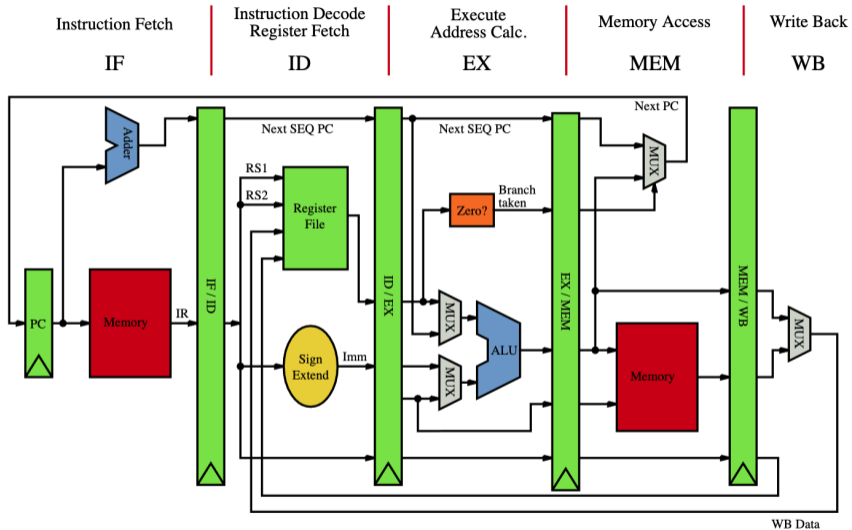


Figure: Pipelined CPU stages. Image credit wikimedia

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Compiling for loops to while loops

C loop statements such as for loops, while loops, and do-while loops do not exist in assembly. They are instead constructed from conditional jump statements.

```
1 unsigned long count_bits_for (
2   unsigned long number
3 ) {
4   unsigned long tally = 0;
5   for (
6     int shift=0; // init
7     shift<8*sizeof(unsigned long); // ←
8     test
9     shift++ // update
10  ) {
11    // body
12    tally += 0b1 & number>>shift;
13  }
14  return tally;
15 }
```

```
1 unsigned long count_bits_while (
2   unsigned long number
3 ) {
4   unsigned long tally = 0;
5   int shift=0; // init
6   while (
7     shift<8*sizeof(unsigned long) // ←
8     test
9  ) {
10    // body
11    tally += 0b1 & number>>shift;
12    shift++; // update
13  }
14  return tally;
15 }
```

Compiling while loops to do-while loops

```
1 unsigned long count_bits_while (
2   unsigned long number
3 ) {
4   unsigned long tally = 0;
5   int shift=0; // init
6   while (
7     shift<8*sizeof(unsigned long) // ←
8     test
9   ) {
10    // body
11    tally += 0b1 & number>>shift;
12    shift++; // update
13  }
14  return tally;
}
```

```
1 unsigned long count_bits_do_while (
2   unsigned long number
3 ) {
4   unsigned long tally = 0;
5   int shift=0; // init
6   do {
7     // body
8     tally += 0b1 & number>>shift;
9     shift++; // update
10  } while (shift<8*sizeof(unsigned long)←
11           )); // test
12  return tally;
}
```

If initial iteration is guaranteed to run, then do one fewer test.

Compiling do-while loops to goto statements

```
1 unsigned long count_bits_do_while (  
2     unsigned long number  
3 ) {  
4     unsigned long tally = 0;  
5     int shift=0; // init  
6     do {  
7         // body  
8         tally += 0b1 & number>>shift;  
9         shift++; // update  
10    } while (shift<8*sizeof(unsigned long)  
11           ); // test  
11    return tally;  
12 }
```

```
1 unsigned long count_bits_goto (  
2     unsigned long number  
3 ) {  
4     unsigned long tally = 0;  
5     int shift=0; // init  
6 LOOP:  
7     // body  
8     tally += 0b1 & number>>shift;  
9     shift++; // update  
10    if (shift<8*sizeof(unsigned long)) { ←  
11        // test  
11        goto LOOP;  
12    }  
13    return tally;  
14 }
```

Loops get compiled into goto statements which are readily translated to assembly.

Compiling goto statements to assembly conditional jump instructions

```
1 unsigned long count_bits_goto (  
2   unsigned long number  
3 ) {  
4   unsigned long tally = 0;  
5   int shift=0; // init  
6 LOOP:  
7   // body  
8   tally += 0b1 & number>>shift;  
9   shift++; // update  
10  if (shift<8*sizeof(unsigned long)) { ←  
11      // test  
12      goto LOOP;  
13  }  
14  return tally;  
}
```

```
count_bits_for:  
count_bits_while:  
count_bits_do_while:  
count_bits_goto:  
    xorl %ecx, %ecx # int shift=0; // init  
    xorl %eax, %eax # unsigned long tally = 0;  
.LOOP:  
    movq %rdi, %rdx # number  
    shrq %cl, %rdx # number>>shift  
    incl %ecx      # shift++; // update  
    andl $1, %edx. # 0b1 & number>>shift  
    addq %rdx, %rax # tally += 0b1 & number>>shi  
    cmpl $64, %ecx # shift<8*sizeof(unsigned lo  
    jne .LOOP      # goto LOOP;  
    ret            # return tally;
```

All C loop statements so far translate to assembly at right.

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