The memory hierarchy: Locality and cache memories

Yipeng Huang

Rutgers University

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Cache, memory, storage, and network hierarchy trends

- Assembly programming view of computer: CPU and memory.
- Full view of computer architecture and systems: +caches, +storage, +network

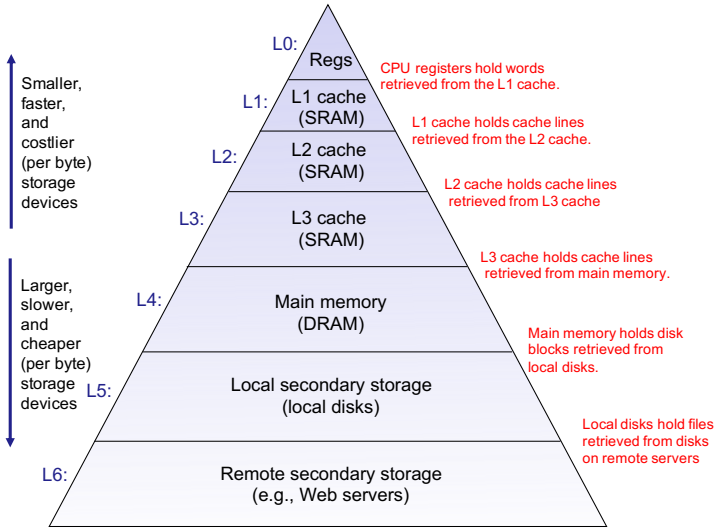

Figure: Memory hierarchy. Image credit CS:APP

Cache, memory, storage, and network hierarchy trends

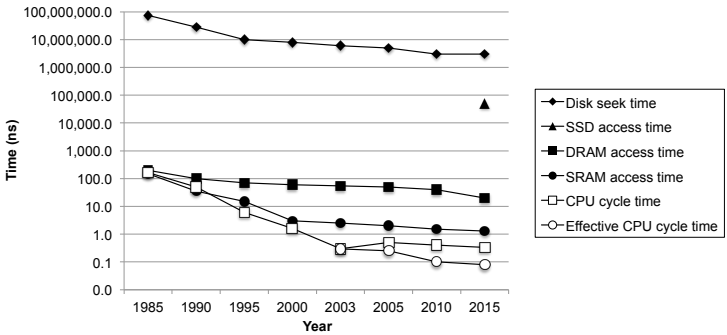

Figure: Widening gap: CPU processing time vs. memory access time. Image credit CS:APP

Topic of this chapter:

- Technology trends that drive CPU-memory gap.
- How to create illusion of fast access to capacious data.

Static random-access memory (registers, caches)

- SRAM is bistable logic
- Access time: 1 to 10 CPU clock cycles
- Implemented in the same transistor technology as CPUs, so improvement has matched pace.

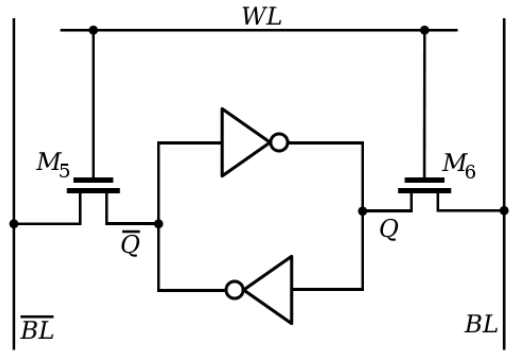

Figure: SRAM operating principle. Image credit Wikimedia

Dynamic random-access memory (main memory)

- Needs refreshing every 10s of milliseconds
- 8GB typical in laptop; 1TB on each ilab machine
- Access time: 100 CPU clock cycles
- Memory gap: DRAM technological improvement slower relative to CPU/SRAM.

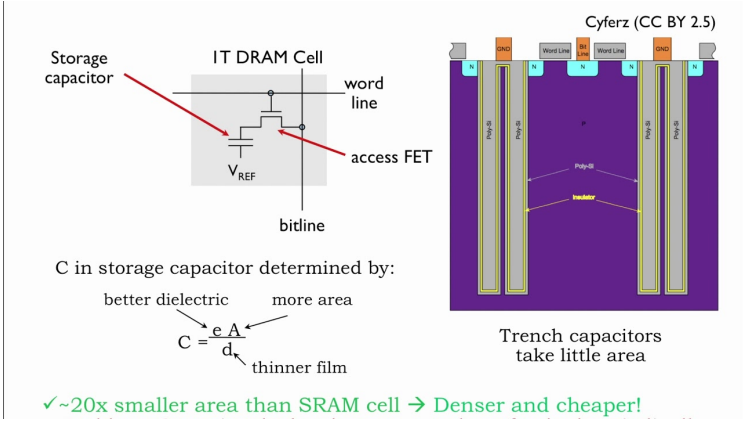

Figure: DRAM operating principle. Image credit ocw.mit.edu

CPU / DRAM main memory interface

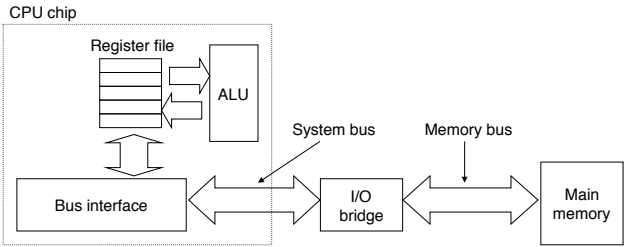

Figure: Memory Bus. Image credit CS:APP

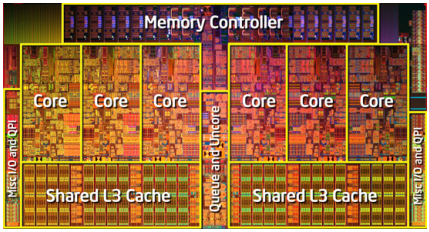

Figure: Intel 2020 Gulftown die shot. Image credit AnandTech

- DDR4 bus standard supports 25.6GB/s transfer rate

Solid state and hard disk drives (storage)

Technology

- SSD: flash nonvolatile memory stores data as charge.
- HDD: magnetic orientation.
- Access time: 100K CPU clock cycles

For in-depth on storage, file systems, and operating systems, take:

- CS214 Systems Programming
- CS416 Operating Systems Design

Since summer 2021, LCSR (admins of iLab) have moved the storage systems that supports everyone's home directories to SSD. `https://resources.cs.rutgers.edu/docs/file-storage/storage-technology-options/`

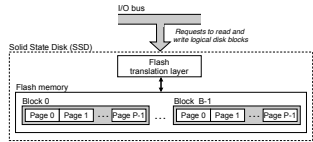

Figure: SSD. Image credit CS:APP

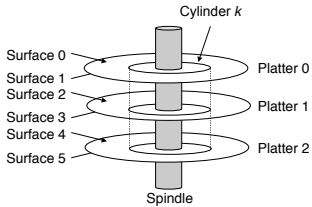

Figure: HDD. Image credit CS:APP

I/O interfaces

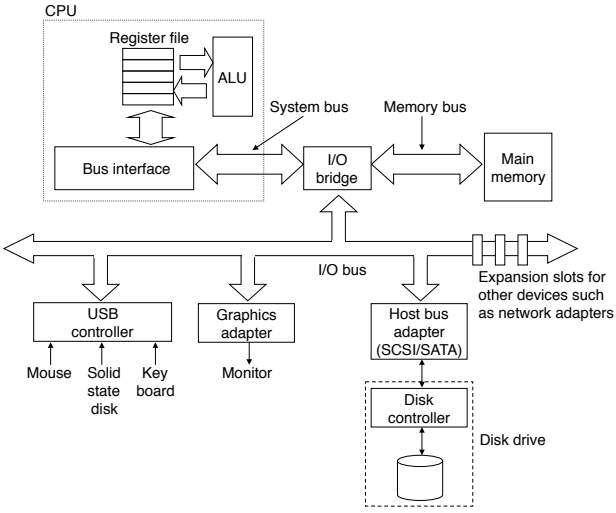

Figure: I/O Bus. Image credit CS:APP

Storage interfaces

- SATA 3.0 interface (6Gb/s transfer rate) typical
- PCIe (15.8 GB/s) becoming commonplace for SSD
- But interface data rate is rarely the bottleneck.

For in-depth on computer network layers, take:

- CS352 Internet Technology

Cache, memory, storage, and network hierarchy trends

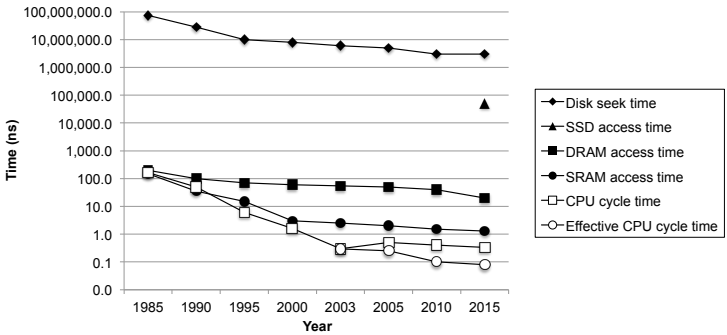

Figure: Widening gap: CPU processing time vs. memory access time. Image credit CS:APP

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Locality: How to create illusion of fast access to capacious data

From the perspective of memory hierarchy, locality is using the data in at any particular level more frequently than accessing storage at next slower level.

First, let's experience the puzzling effect of locality in `sumArray.c`

- sumArrayRows()
- sumArrayCols()

Well-written programs maximize locality

- Spatial locality
- Temporal locality

Spatial locality

```
1  double dotProduct (
2    double a[N],
3    double b[N],
4  ) {
5    double sum = 0.0;
6    for(size_t i=0; i<N; i++){
7      sum += a[i] * b[i];
8    }
9    return sum;
10 }
```

Spatial locality

- Programs tend to access adjacent data.
- Example: stride 1 memory access in `a` and `b`.

Temporal locality

```
1  double dotProduct (
2    double a[N],
3    double b[N],
4  ) {
5    double sum = 0.0;
6    for(size_t i=0; i<N; i++){
7      sum += a[i] * b[i];
8    }
9    return sum;
10 }
```

Temporal locality

- Programs tend to access data over and over.
- Example: `sum` gets accessed N times in iteration.

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CPU / cache / DRAM main memory interface

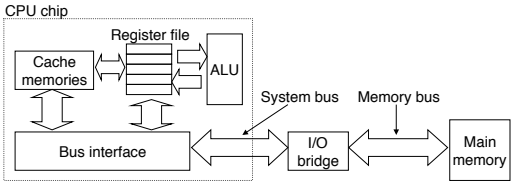

Figure: Cache resides on CPU chip close to register file. Image credit CS:APP

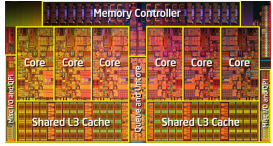

Figure: Intel 2020 Gulftown die shot. Image credit AnandTech

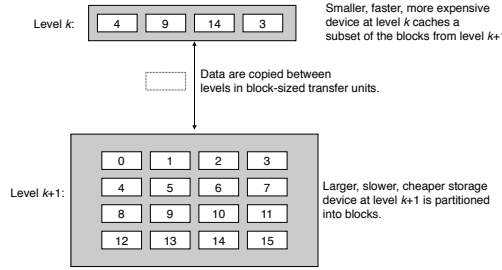

Figure: Cache stores a temporary copy from the slower main memory. Image credit CS:APP

CPU / cache / DRAM main memory interactions

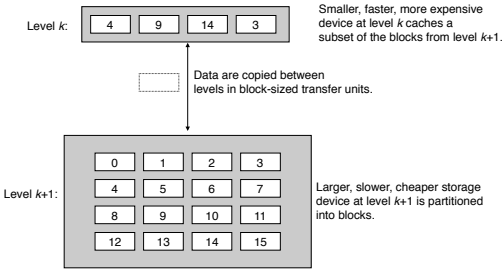

Figure: Cache stores a temporary copy from the slower main memory. Image credit CS:APP

When CPU loads (LD) from memory

- Cache read hit
- Cache read miss

When CPU stores (ST) to memory

- Cache write hit
- Cache write miss

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Cache placement policy (how to find data at address for read and write hit)

Several designs for caches

- Fully associative cache
- Direct-mapped cache
- N-way set-associative cache

Cache design options use m-bit memory addresses differently

- t-bit tag
- s-bit set index
- b-bit block offset

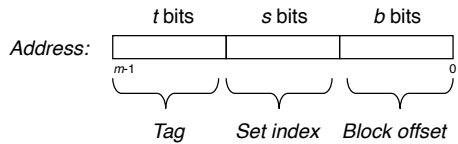


Figure: Memory addresses. Image credit CS:APP

Fully associative cache

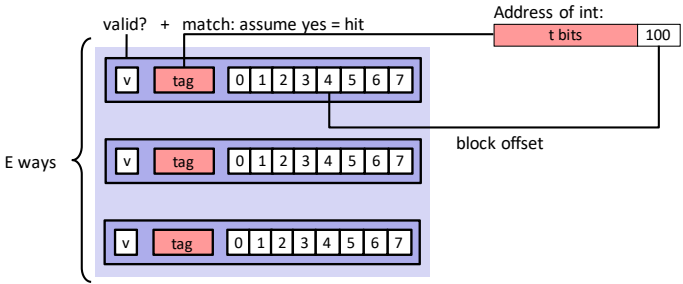


Figure: Fully associative cache. Image credit CS:APP

m-bit memory address split into:

- *t*-bit tag
- *b*-bit block offset

Fully associative cache

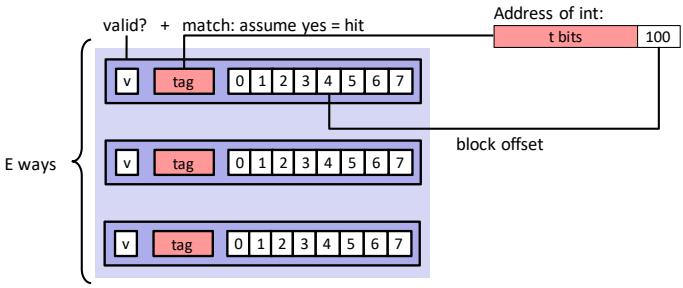


Figure: Fully associative cache. Image credit CS:APP

b-bit block offset

- here, $b = 3$
- The number of bytes in a block is $B = 2^b = 2^3 = 8$
- A block is the minimum number of bytes that can be cached
- Good for capturing spatial locality, short strides

Fully associative cache

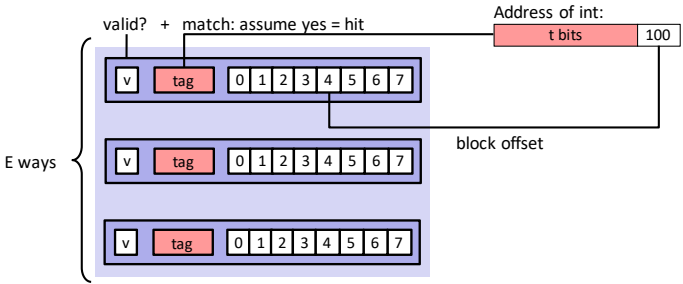


Figure: Fully associative cache. Image credit CS:APP

t-bit tag

- here, $t = m - b = m - 3$
- When CPU wants to read from or write to memory, all t-bits in tag need to match for read/write hit.

Fully associative cache

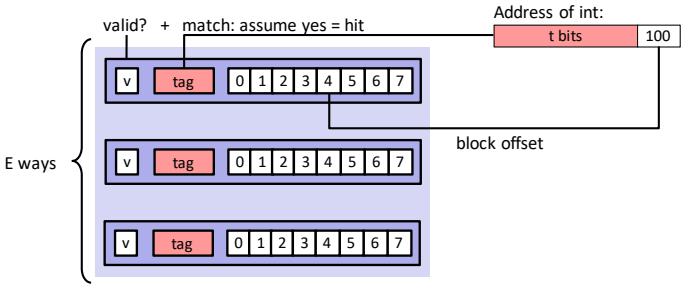


Figure: Fully associative cache. Image credit CS:APP

Full associativity

- Blocks can go into any of E ways
- Here, $E = 3$
- Good for capturing temporal locality: cache hits can happen even with intervening reads and writes to other tags.

Fully associative cache

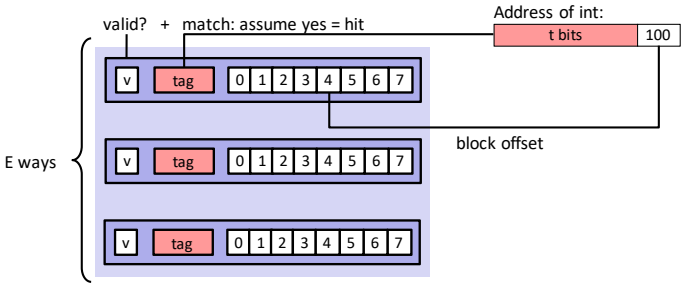


Figure: Fully associative cache. Image credit CS:APP

Capacity of cache

- Total capacity of fully associative cache in bytes: $C = EB = E * 2^b$
- Here, $C = E * 2^b = 3 * 2^3 = 24$ bytes

Fully associative cache

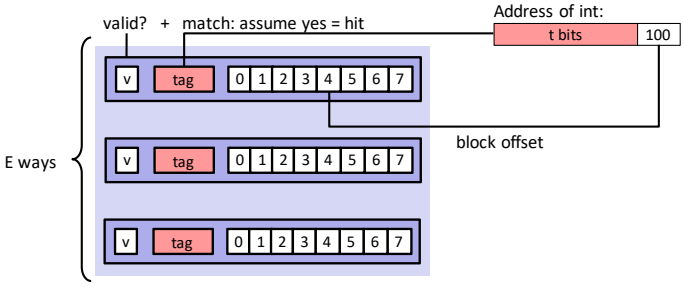


Figure: Fully associative cache. Image credit CS:APP

Strengths

- Blocks can go into any of E-ways.
- Hit rate is only limited by total capacity.

Weaknesses

- Searching across all valid tags is expensive.
- Figuring out which block to evict on read/write miss is also expensive.
- Requires a lot of

Direct-mapped cache

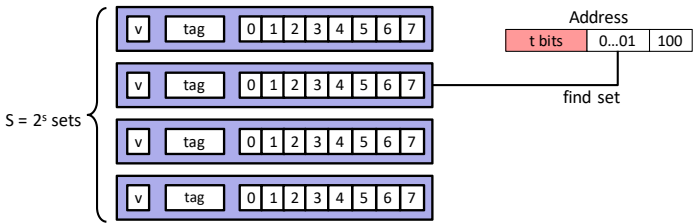


Figure: Direct-mapped cache. Image credit CS:APP

m-bit memory address split into:

- *t*-bit tag
- *s*-bit set index
- *b*-bit block offset

Direct-mapped cache

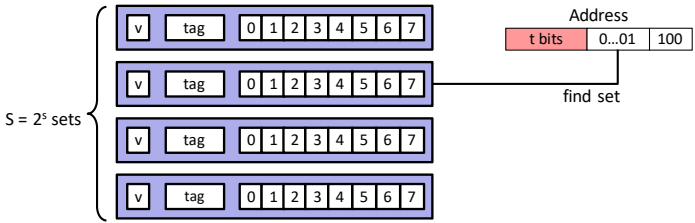


Figure: Direct-mapped cache. Image credit CS:APP

b-bit block offset

- here, $b = 3$
- The number of bytes in a block is $B = 2^b = 2^3 = 8$
- A block is the minimum number of bytes that can be cached
- Good for capturing spatial locality, short strides

Direct-mapped cache

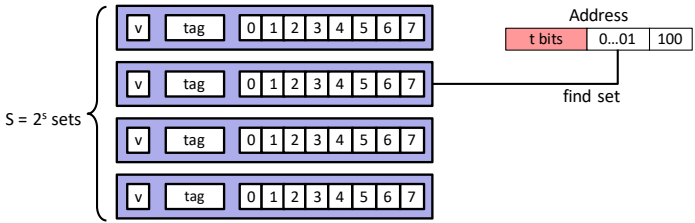


Figure: Direct-mapped cache. Image credit CS:APP

s-bit set index

- here, $s = 2$
- The number of sets in cache is $S = 2^s = 2^2 = 4$
- A hash function that limits exactly where a block can go
- Good for further increasing ability to exploit spatial locality, short strides

Direct-mapped cache

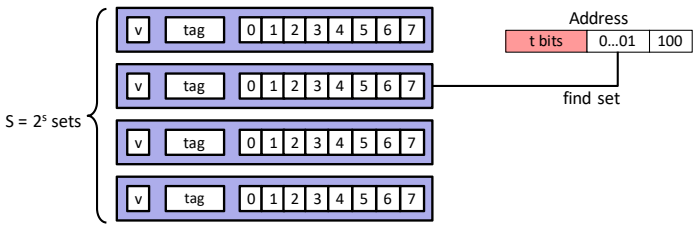


Figure: Direct-mapped cache. Image credit CS:APP

t-bit tag

- here, $t = m - s - b = m - 2 - 3$
- When CPU wants to read from or write to memory, all t-bits in tag need to match for read/write hit.

Direct-mapped cache

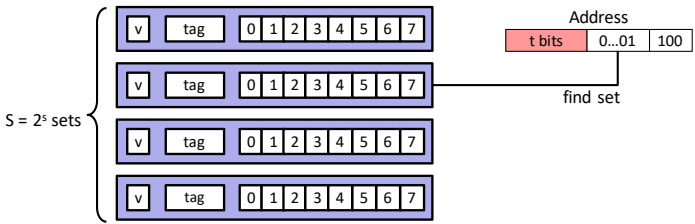


Figure: Direct-mapped cache. Image credit CS:APP

Direct mapping

- In direct-mapped cache, blocks can go into only one of $E = 1$ way

Direct-mapped cache

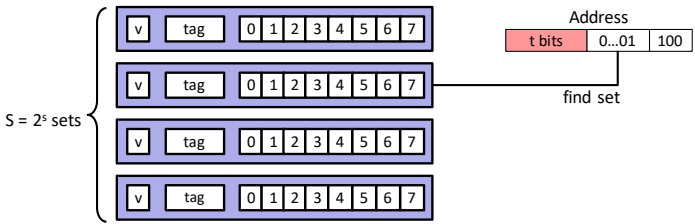


Figure: Direct-mapped cache. Image credit CS:APP

Capacity of cache

- Total capacity of fully associative cache in bytes:
  $C = SEB = 2^s * E * 2^b$
- Here, $C = 2^s * E * 2^b = 2^2 * 1 * 2^3 = 32$ bytes

Direct-mapped cache

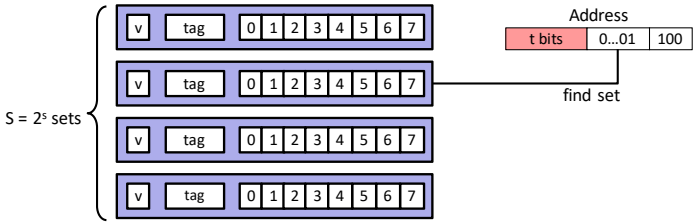


Figure: Direct-mapped cache. Image credit CS:APP

Strengths

- Simple to implement.
- No need to search across tags.

Weaknesses

- Can lead to surprising thrashing of cache with unfortunate access patterns.
- Unexpected conflict misses independent of cache capacity.

E-way set-associative cache

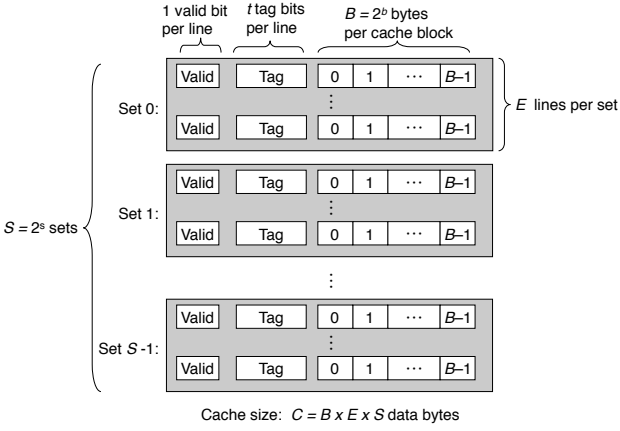


Figure: Direct-mapped cache. Image credit CS:APP

Strengths

- Blocks can go into any of E-ways, increases ability to support temporal locality, thereby increasing hit rate.
- Only need to search across E tags. Avoids costly searching across all valid tags.
- Avoids conflict misses due to unfortunate access patterns.

E-way set-associative cache

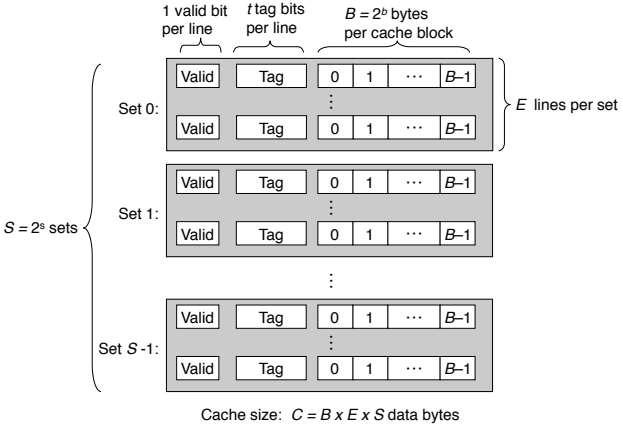
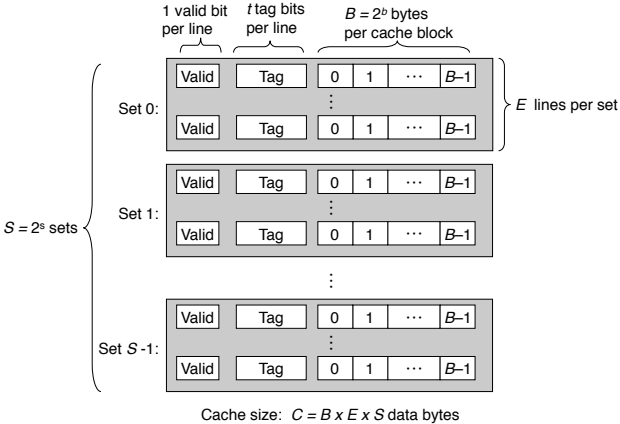


Figure: Direct-mapped cache. Image credit CS:APP

Used in practice in, e.g., a recent Intel Core i7:

- $C = 32$KB L1 data cache per core
- $S = 64 = 2^6$ sets/cache ($s = 6$ bits)
- $E = 8 = 2^3$ ways/set
- $B = 64 = 2^6$ bytes/block ($b = 6$ bits)
- $C = S * E * B$
- Assuming memory addresses are $m = 48$, then tag size $t = m - s - b = 48 - 6 - 6 = 36$ bits.

E-way set-associative cache



Let's see textbook slides for a simulation

Figure: Direct-mapped cache. Image credit CS:APP

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PA5: Simulating a cache and optimizing programs for caches

Write a cache simulator

1. fullyAssociative
2. directMapped
3. setAssociative

Optimize some code for better cache performance

1. cacheBlocking
2. cacheOblivious

PA5: Simulating a cache and optimizing programs for caches

A tour of files in the package

- trace files
- csim-ref